Phase conjugation with Zelda wavefront sensor

A manual closure of a loop on the MITHIC bench

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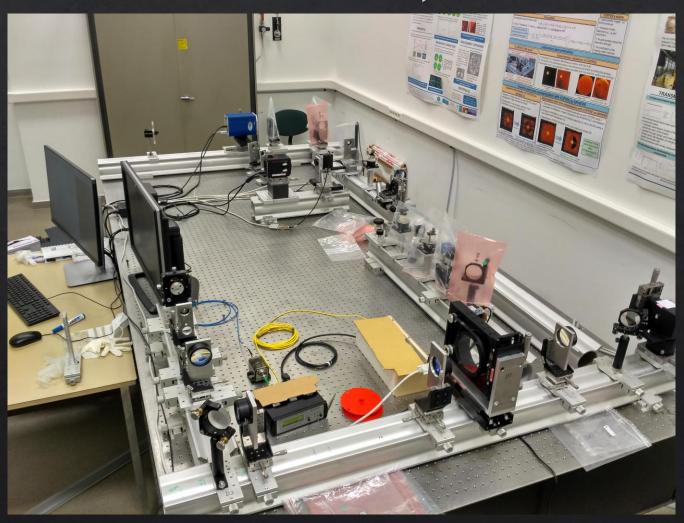
In collaboration with Kjetil DOHLEN, Arthur VIGAN, Jean-François SAUVAGE, Thierry FUSCO



High-contrast imaging

- MITHIC: experimental test bench used to validate concepts for High-Contrast imaging
- \Rightarrow High-contrasts :~10⁹ for future instruments
- Deleting light by interferences
- Need of a very flat wavefront to avoid speckles (nanometric RMS)

MITHIC (Marseille Imaging Testbed for HIgh Contrast)



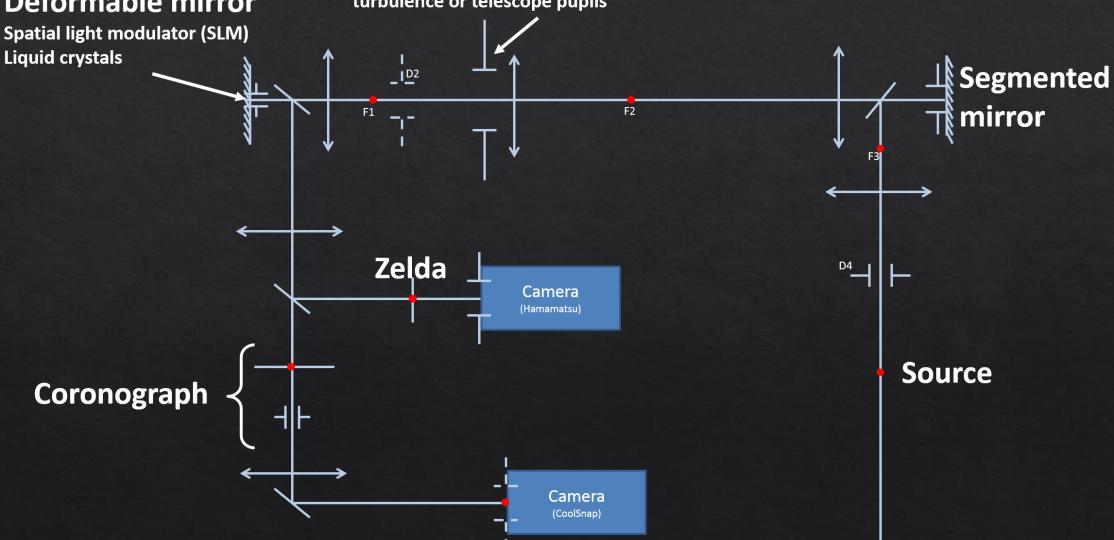
Wavelenght used : $\lambda = 670 \text{ nm}$

MITHIC: principle

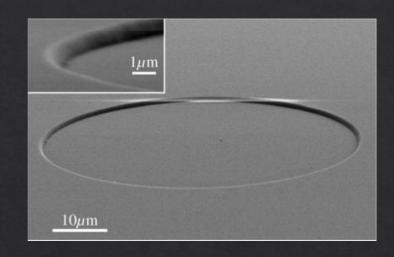
Phase screen

Deformable mirror

Carved glass simulating either remaining turbulence or telescope pupils



ZELDA (Zernike sensor for Extremely Low-level Differential Aberrations)



- \Leftrightarrow Phase mask introducing a $\lambda/4$ phase shift on a half of the PSF (a diameter of approx. F* $\lambda \sim 60 \, \mu m$)
- ♦ Invented by Zernike in the 30's (for microscopy); Nobel prize in 1953
- Transforms the phase defects into intensity defects (in the pupil plane)
- Short linearity range but a high sensibility (sub-nanometric)

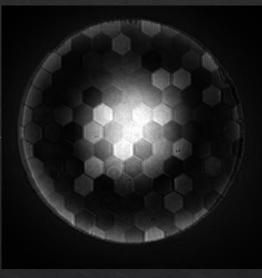
Goals of the work

- Closing a loop between Zelda and the SLM (simulating a deformable mirror):
 - without any interaction matrix (non-automized bench => « slow » speed
 of measurement)
 - Phase conjugation principle

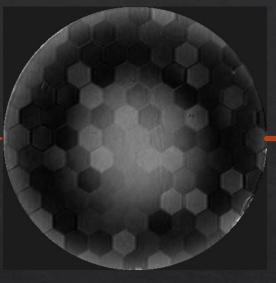
- Stabilizing the loop
 - ♦ Non optimized because of geometrical/gain problems

Princple of the phase conjugation

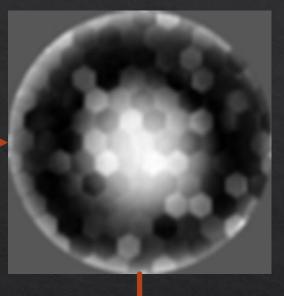
Aquisition of a Zelda image



Computation of the OPD



Processing the OPD

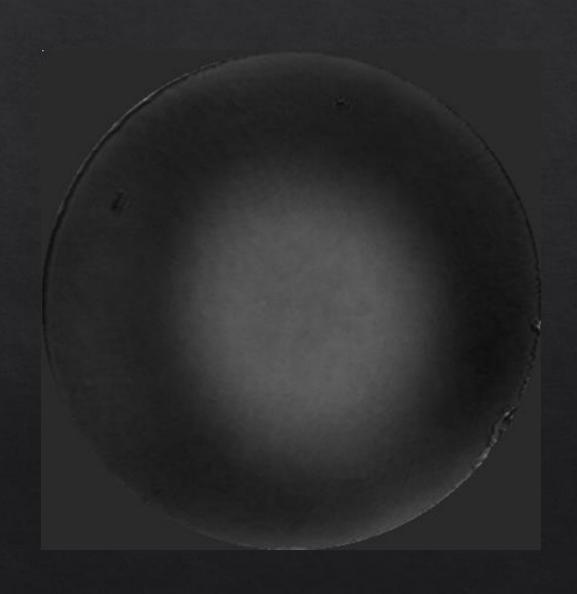


Application on the SLM

First encouraging results

Aberrations introduced on the phase screen: Segmented pistons Not corrected – RMS ~80 nm After one iteration After 2 iterations After 3 iterations – RMS~40 nm Random Zernike Polynoms (simulating Non-Common Path Aberrations)

Some correction errors



Fourier transform analysis

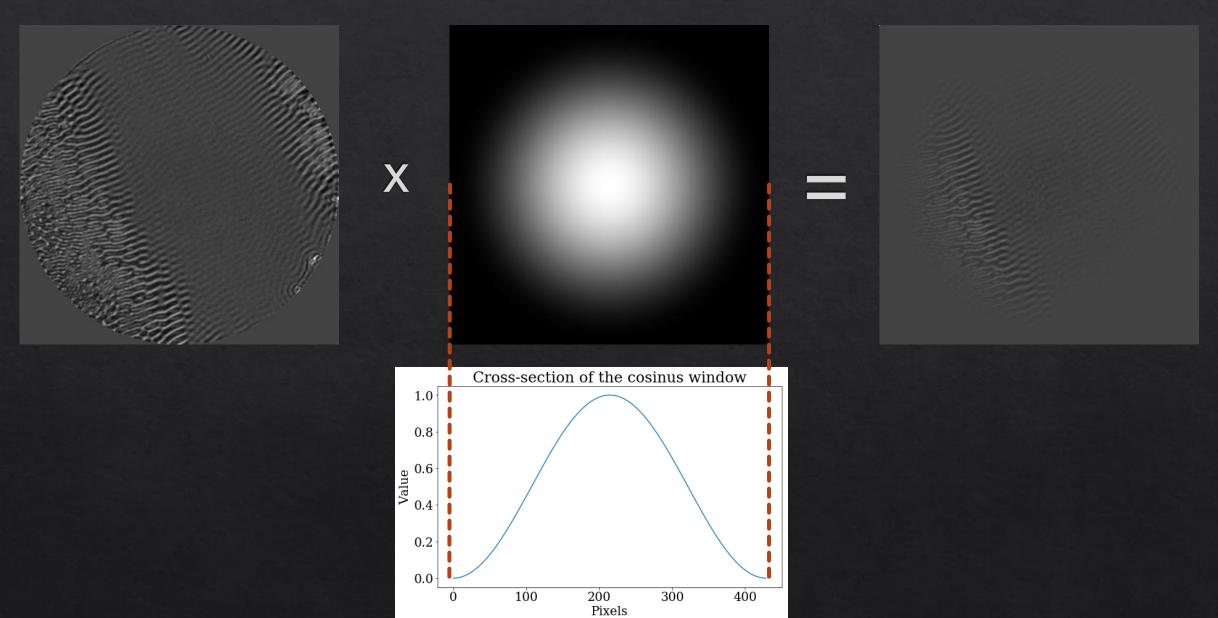


« Non-apodised » pupil

« Apodised » pupil

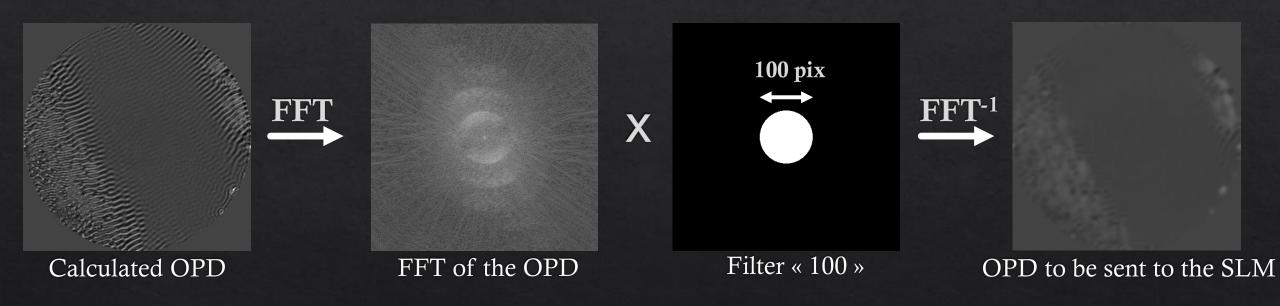
« Apodised » pupil -Filtered sequence

Apodised pupil

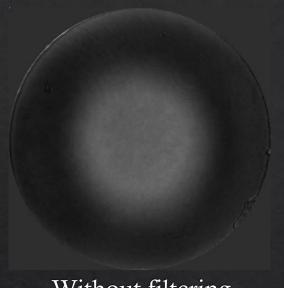


Filtering

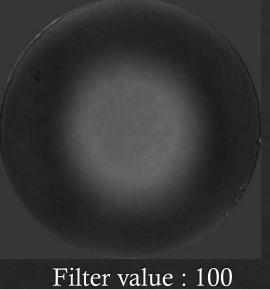
♦ How do we « measure » filter?

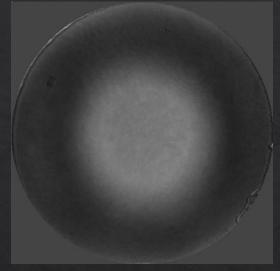


Different filter values

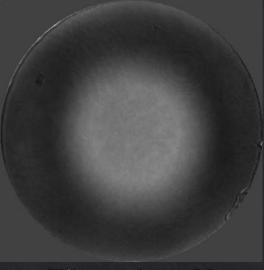


Without filtering

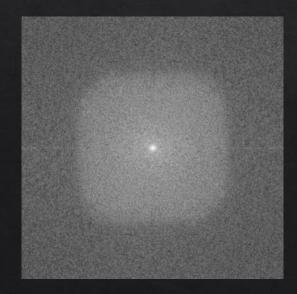


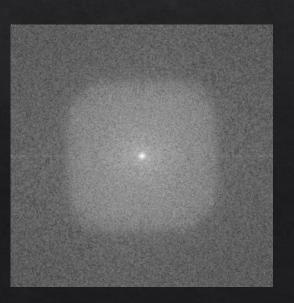


Filter value: 50

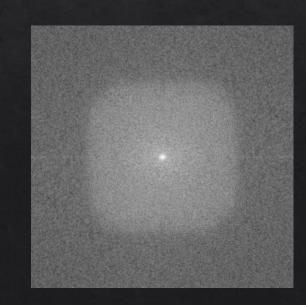


Filter value: 20

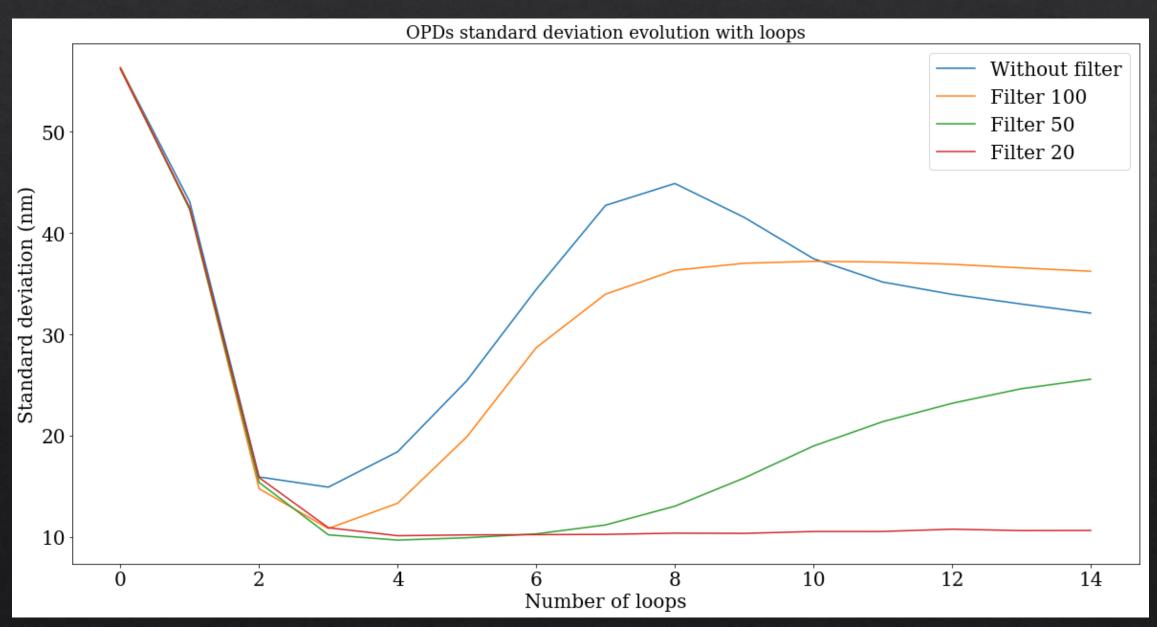




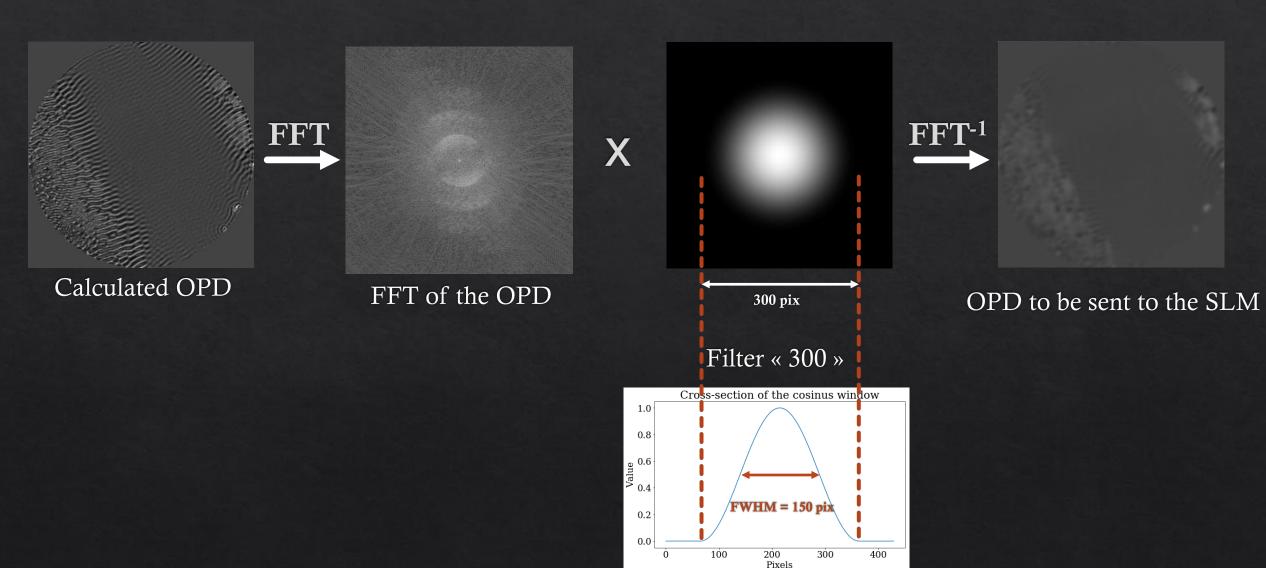




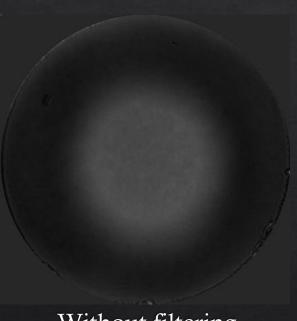
Filtering



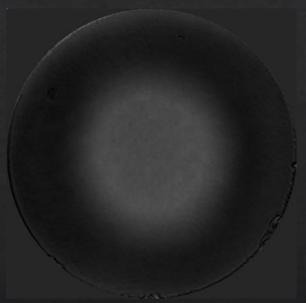
Apodised filtering



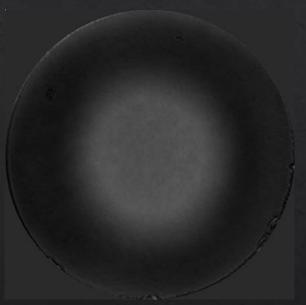
Apodised filtering



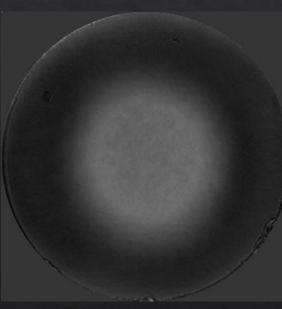
Without filtering



Filter value: 250

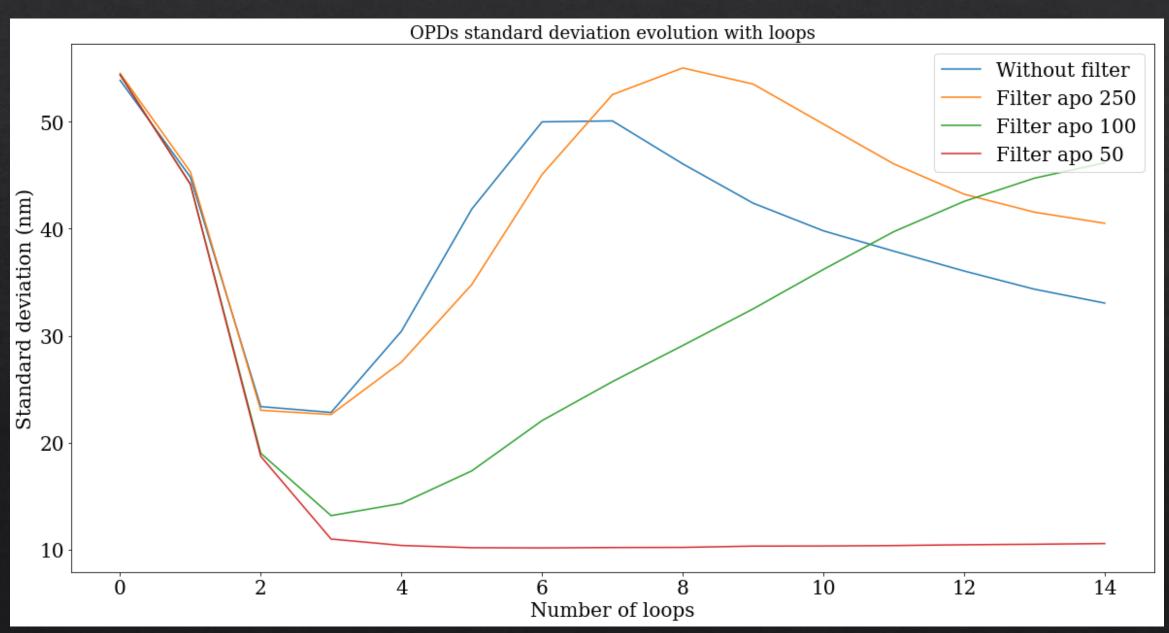


Filter value: 100



Filter value : 50

Apodised filtering

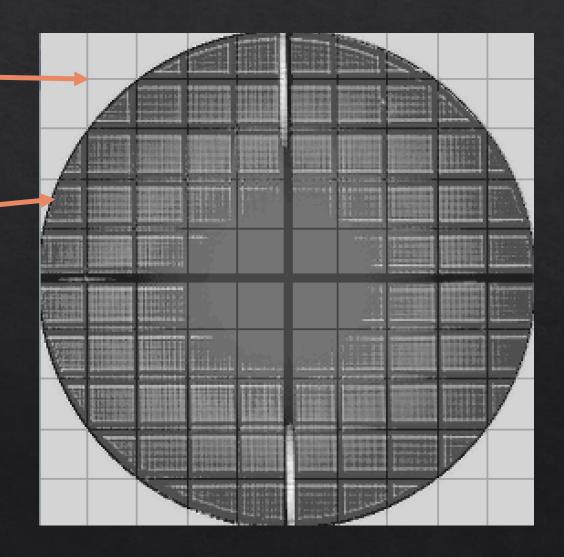


Detection of deformation

♦ Placing a grid on the SLM

♦ Analyzing the image (Zeldagram) of the grid

♦ Non-uniform deformation => distortion



Analysis of deformation

Gaussian dots on the SLM

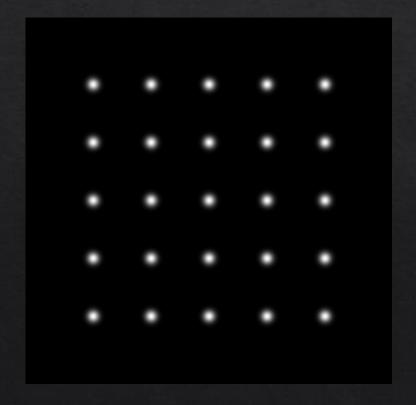
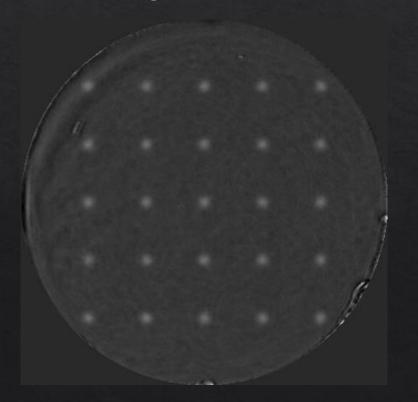
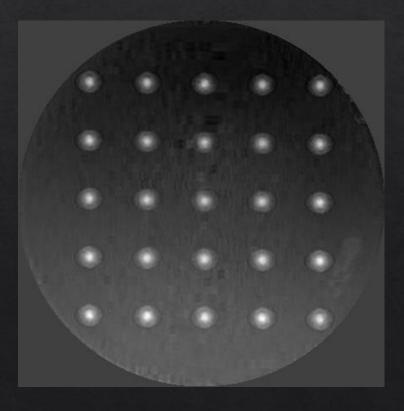


Image of the dots



Deduced OPD



Caculation of deformation

U: Values sent to the SLM

U': Values from Zelda

Transformation *f* computed :

$$f: U' \to U$$

$$f(U') = MU + C$$

With M a 2*2 matrix and C a 2*1 vector

Results from computation

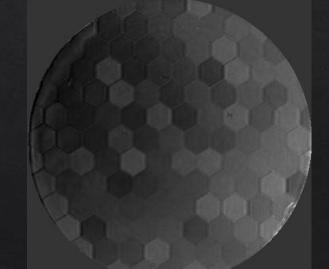
$$M = \begin{pmatrix} 1,00513 & -0,00084 \\ 0,01583 & 0,99277 \end{pmatrix}$$

$$\diamond C = \begin{pmatrix} -3.34632 \\ -5.83732 \end{pmatrix}$$

- ♦ Max residual error: 0.55 pix
- ♦ Mean error: 0.19 pix
- ♦ Error standard deviation: 0.13 pix

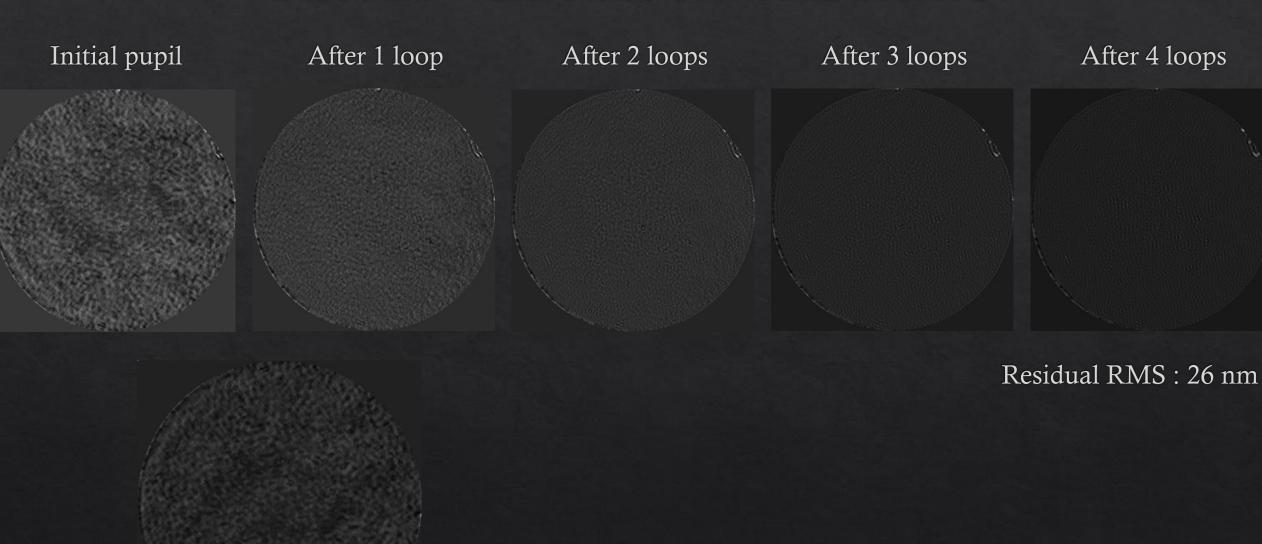
Results with a segmented pupil



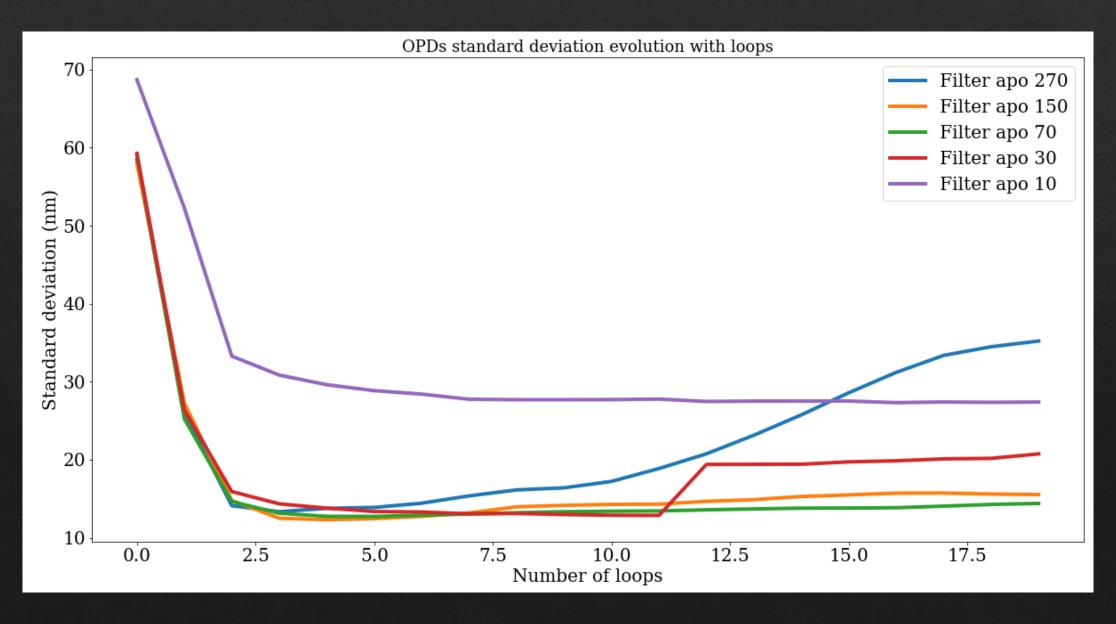


Residual RMS: 28 nm

Results with random turbulence



Apodised filtering + correction of deformation (gain = 0.7)

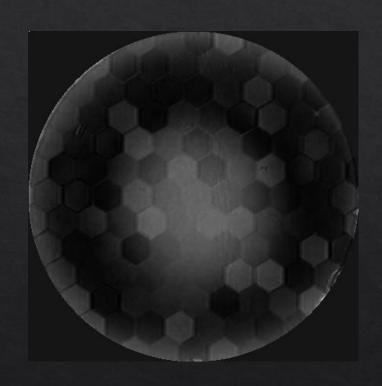


Remaining issues

Remaining (but smaller) wrinkles (even with antialiasing)

Some astigmatism in the pupil conjugation

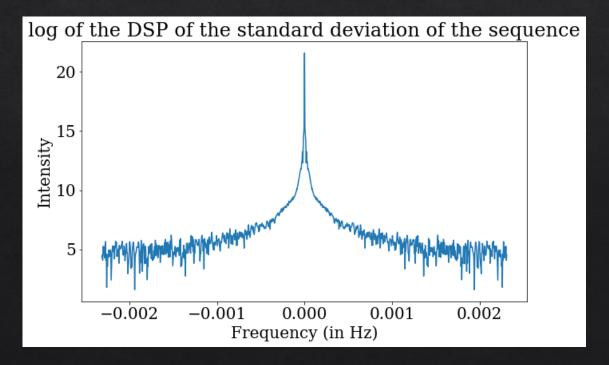
Dust on sensible components



Time evolution analysis

 Some (but non-disturbing) high frequencies

♦ 0.0046 Hz (1000 images in ~60 hours)





1st phase substracted– 10 Hz

Perspectives for the bench

- ♦ Automatize the bench (in progress) for easier measurement (in a unique interface for all elements)
- Remotely operate the bench?
- ♦ Calibration of the NCPA
- ♦ Real-time correction of perturbation
- ♦ Compute an interaction matrix for optimal correction
- ♦ Fully characterize the bench (how does the mask move with time) and heat

Acknowledgments

Kjetil DOHLEN, Arthur VIGAN, Jean-François SAUVAGE, Amandine CAILLAT, Thierry FUSCO, Mamadou N'DIAYE