



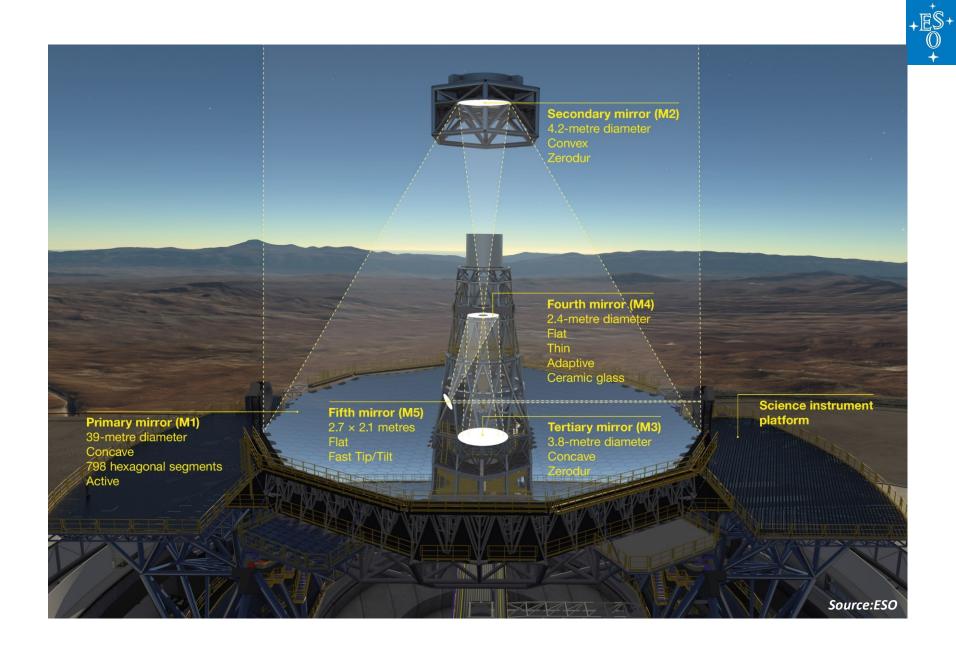


Risk mitigation for the ELT segments phasing

R&D SEMINAR

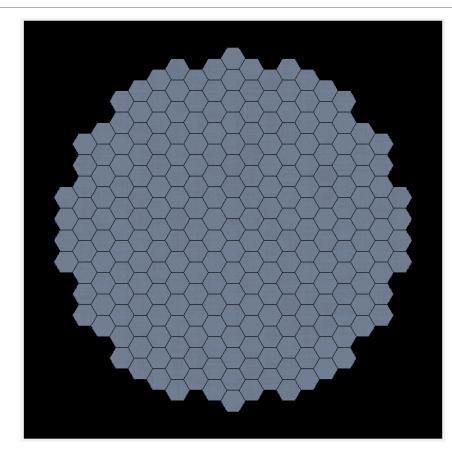
ANNE-LAURE CHEFFOT EUROPEAN SOUTHERN OBSERVATORY / AIX MARSEILLE UNIVERSITY







Primary mirror segmentation



Critical numbers

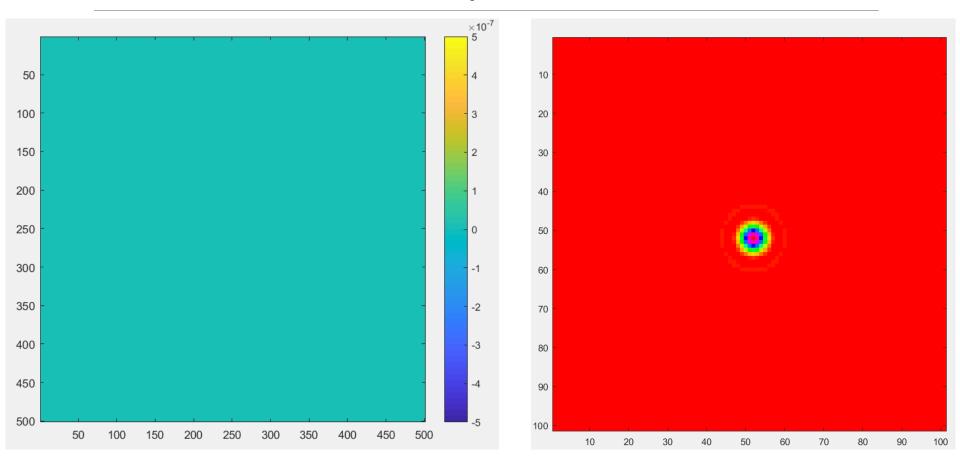
- 39 meters diameter
- 798 segments
- 1.4m corner to corner
- 4mm gap between segments
- Controlled in Tip/Tilt Piston

And also ...

- > 7000 edge sensors
- > 7000 actuators

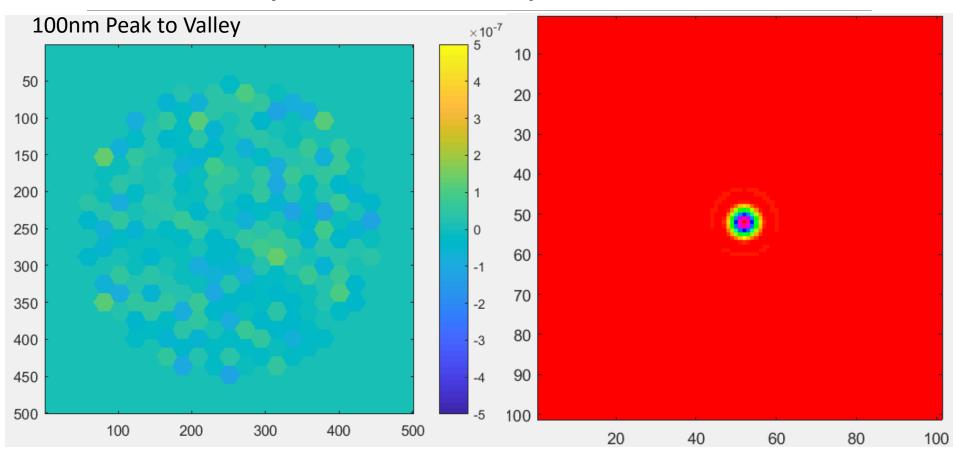


Perfect telescope



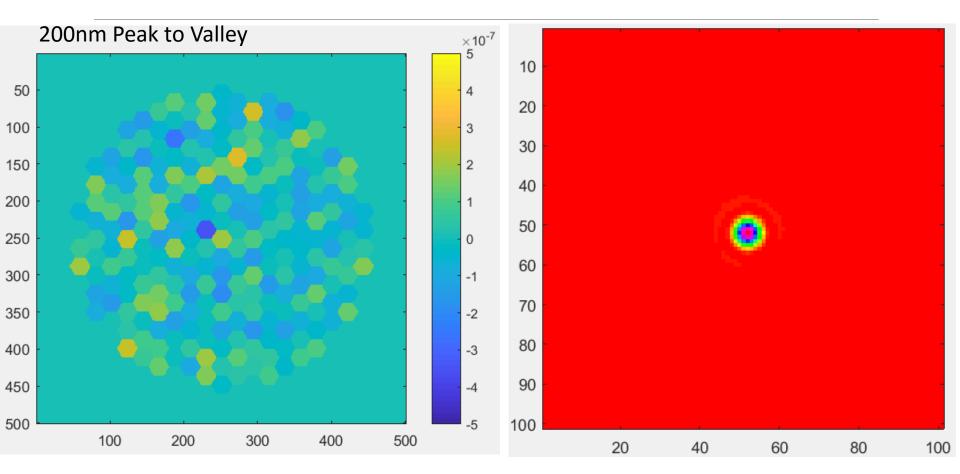


Not so perfect any more



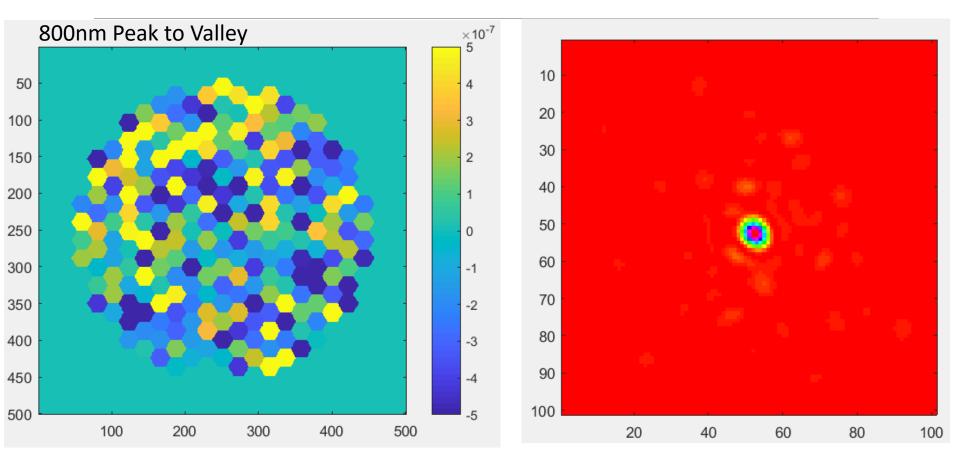


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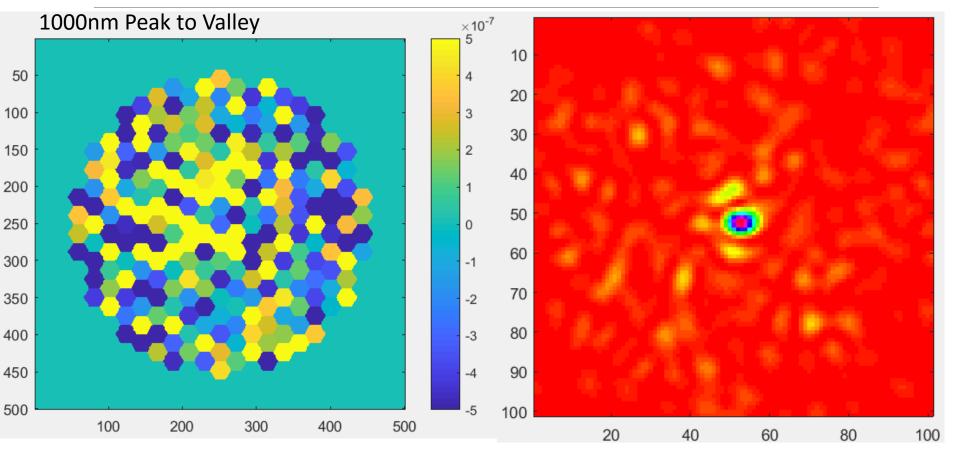


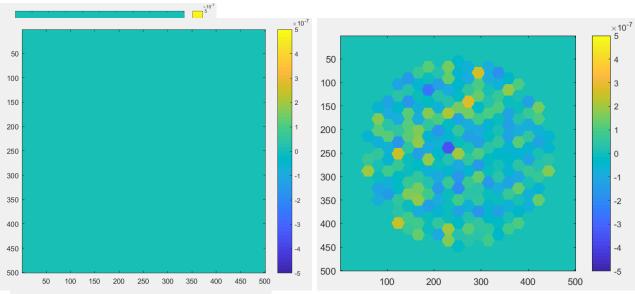
. . .

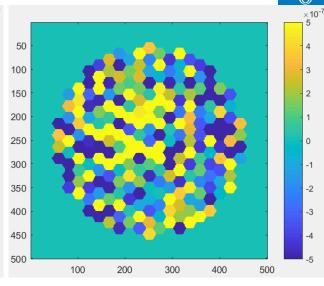


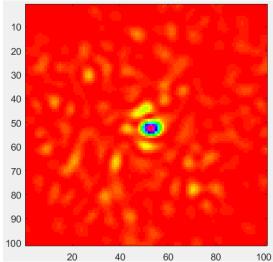


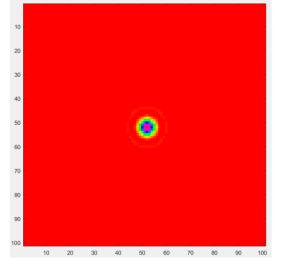
Completely banana

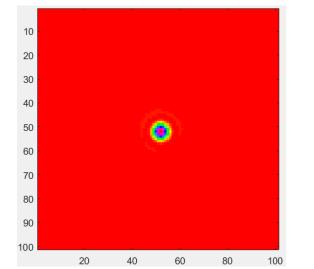




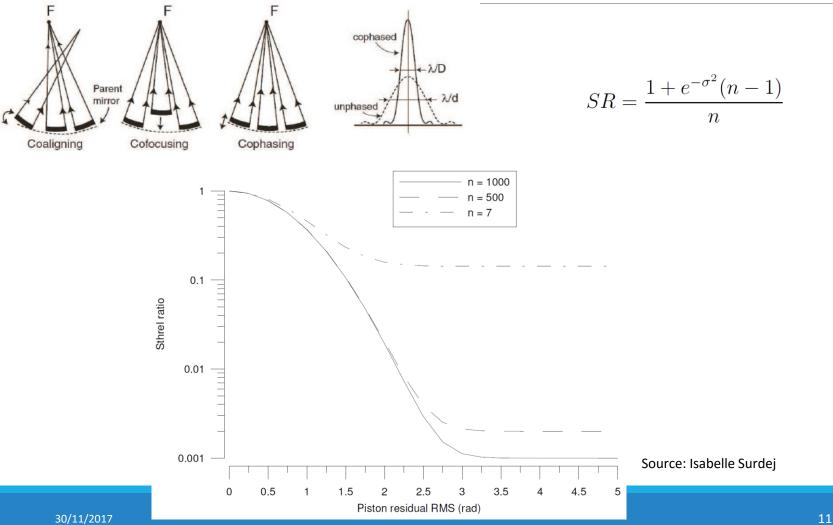






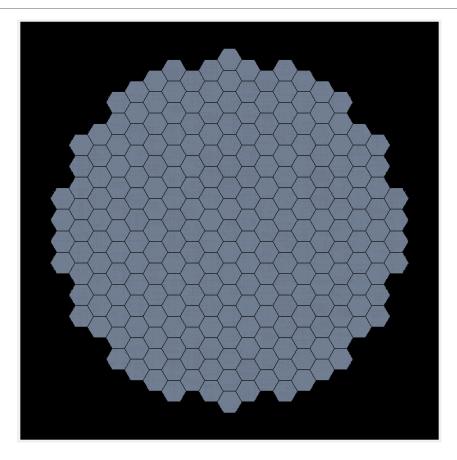


N=number of segments σ = residual RMS phasing error





Can you see something?





Challenge



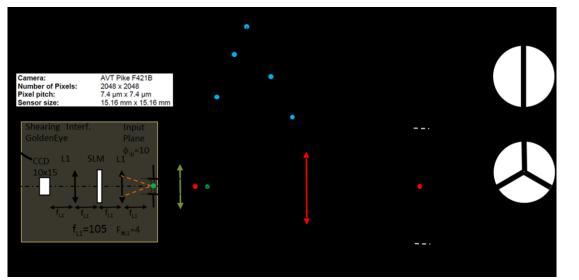


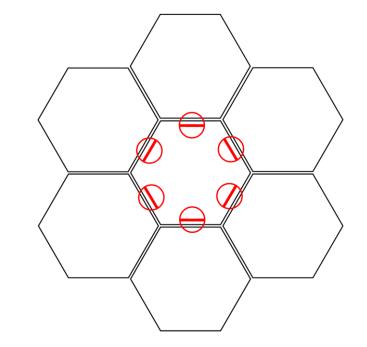
Solution





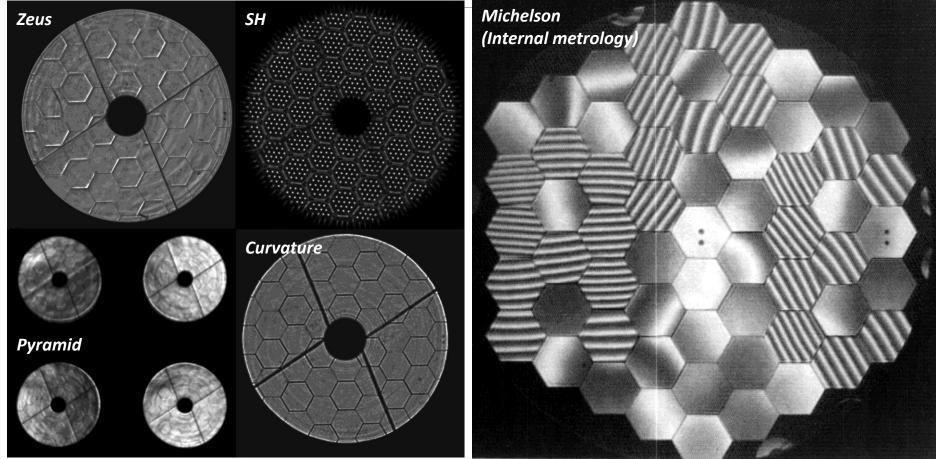
Look at it locally







Look at it globally



Active Phasing Experiment – ESO/VLT - 2009

30/11/2017



Overview

Baseline for the ELT primary

- One phasing run on sky every two weeks using Shack-Hartmann
- Two freshly recoated segment re-installed on M1 per day

Risks

- High sensitivity to registration error (consequence of high segmentation)
- Degradation of the phasing over 2 weeks

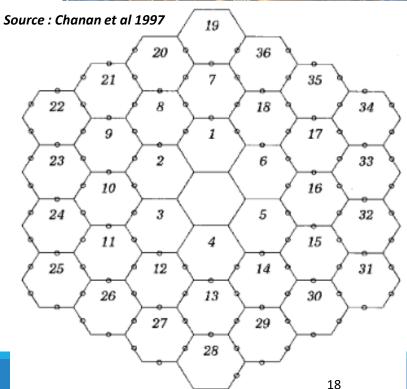
Mitigation

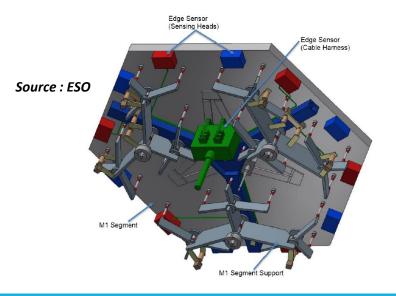
- Pupil plan phasing sensor to mitigate registration error
- Monitor the phasing during observation
- Phasing of one segment after replacement during sunny hours

Phasing Baseline: Keck approach

- Shack-Hartmann mask phasing sensor
- No phasing during observation:
 → high performance Edge sensor
- Maintenance









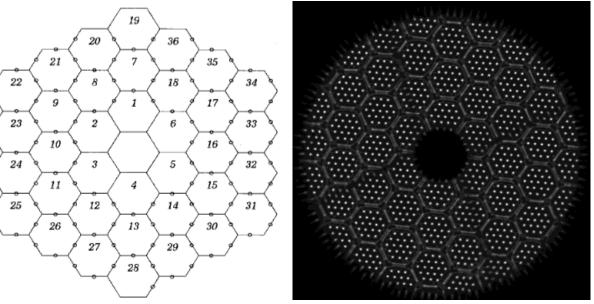
Risk assessment

Baseline	One phasing run on sky every two weeks using Shack-Hartmann
 Associated risk 	 High sensitivity to registration error Degradation of the phasing
Baseline	Two freshly recoated segment re-installed on M1 per day
 Associated risk 	 Degradation of the phasing

How to mitigate?



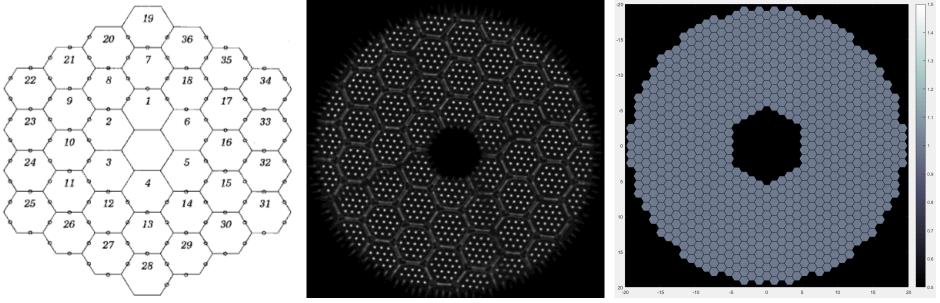
Registra...What?



Pupil plane phasing sensor to mitigate registration error



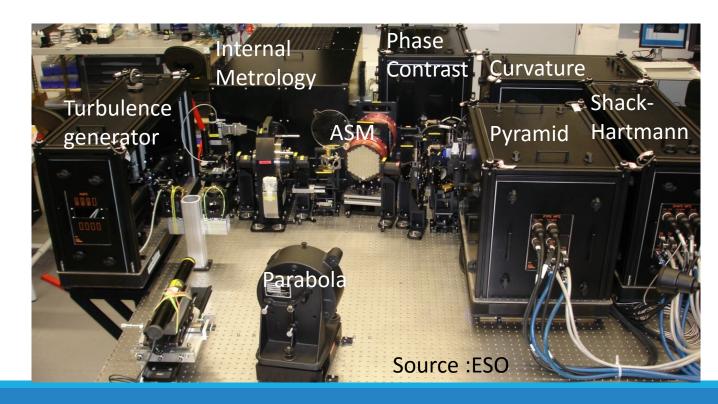
Registra...What?

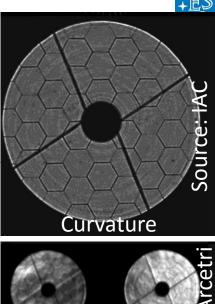


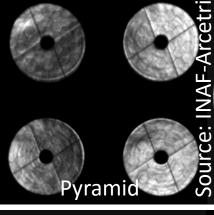
Pupil plane phasing sensor to mitigate registration error

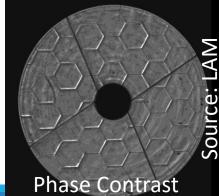
Active Phasing Experiment

• ASM :Active Segmented Mirror (61 Segment)





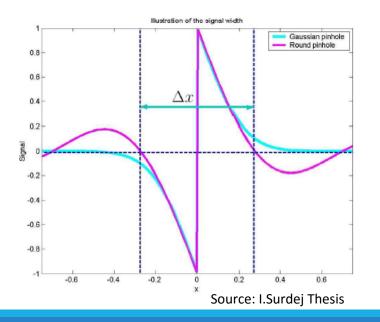


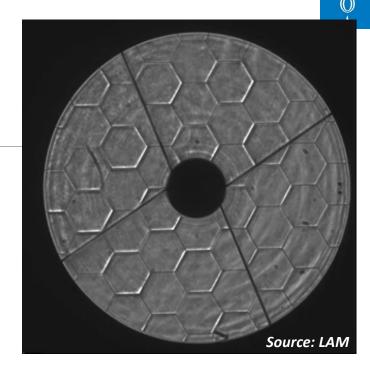


Phase contrast sensor

• ZErnike Unit Sensor (LAM)

Monitoring phasing during observation





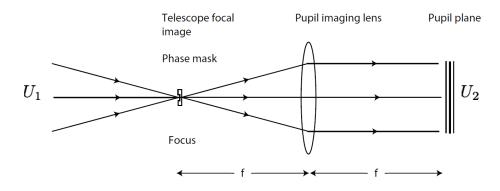


Figure 5.1: Zernike phasing sensor layout: After the filtering of the incoming wavefront U_1 by the phase mask (shown in detail in Fig. 5.2) in the focal plane, the pupil is re-imaged on the detector plane, U_2 , by a pupil re-imaging lens of focal length f.

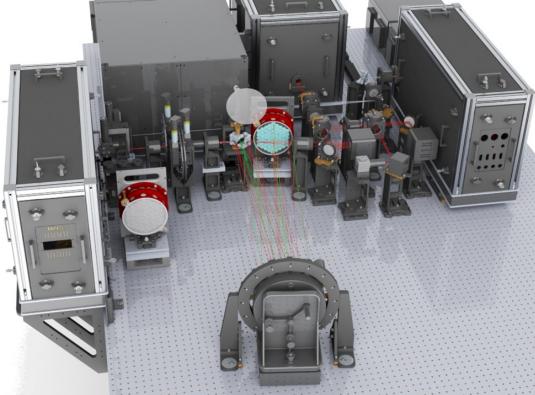
Source: I.Surdej Thesis



Monitor the phasing during observations

<u>Phasing the ELT with Adaptive optics</u> <u>Control</u> <u>Experiment</u> (PEACE),

- Investigate cross-performance with AO
- ➤ ZEUS → wavelength scan to increase capture range?





Monitor the phasing during observations

<u>Phasing the ELT with Adaptive optics</u> <u>Control</u> <u>Experiment</u> (PEACE),

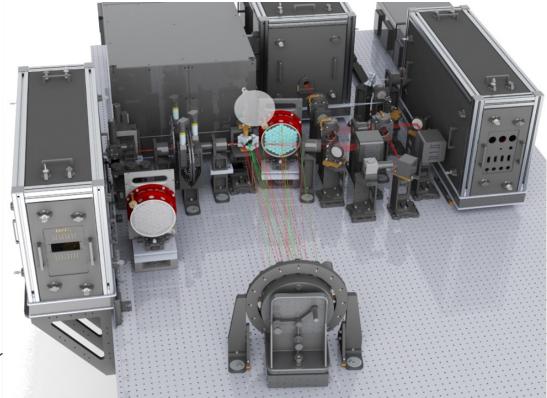
- Investigate cross-performance with AO
- ➤ ZEUS → wavelength scan to increase capture range?

On going refurbishment

• Metrology = Edge Sensor

Addition to fit ELT baseline

- ELT Spider
- Adaptive Optics Segmentatior



Local phasing \rightarrow phasing gun



Local phasing

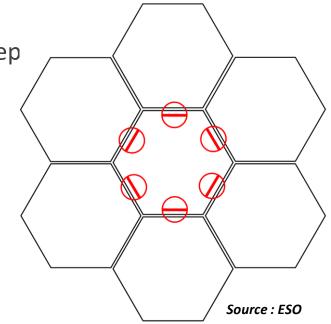
Two freshly recoated segment re-installed on M1 per day

Edge sensor: no phasing while observing

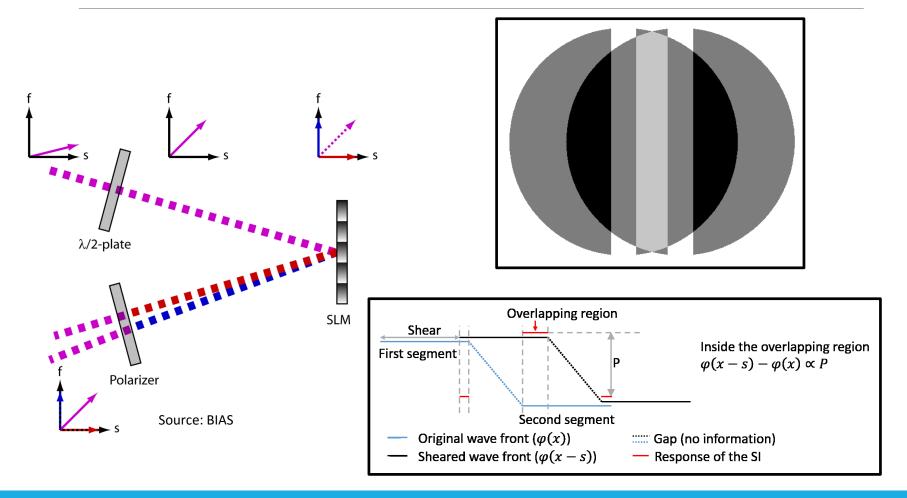
• Reference lost

Day time phasing of one segment after rep

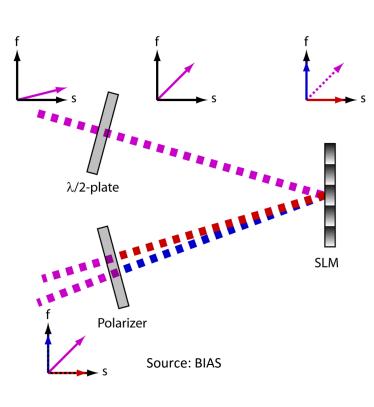
- Range +-200um
- Precision~10-20nm

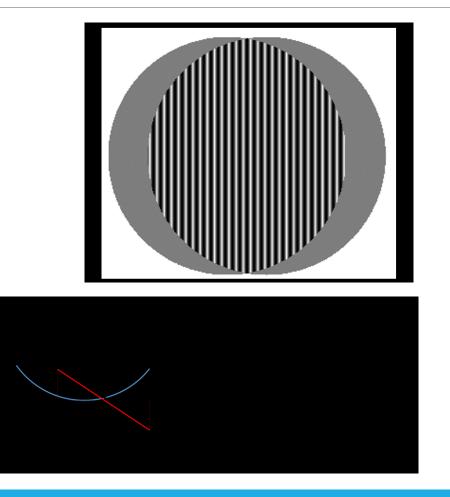




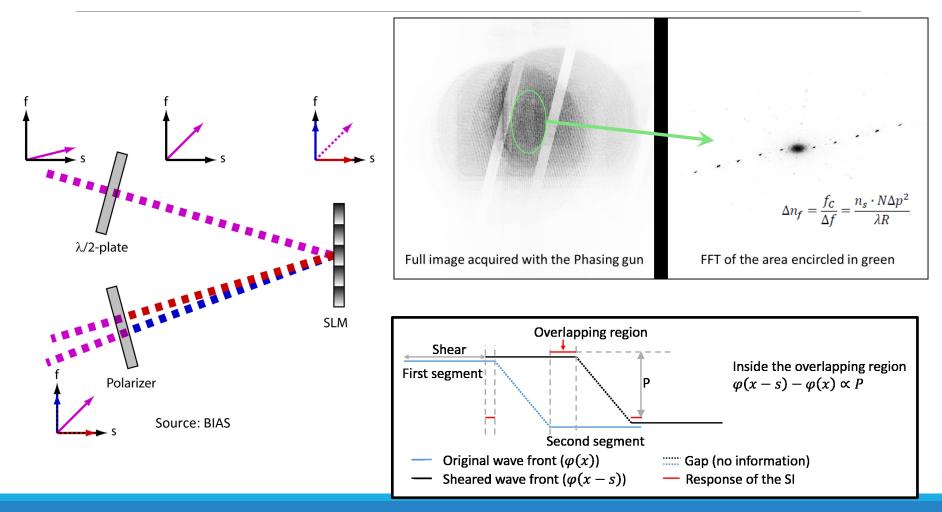












ELT M1 facility

ES

+ Эп

ELT M1 facility + Phasing gun

Scale 1:1 segment

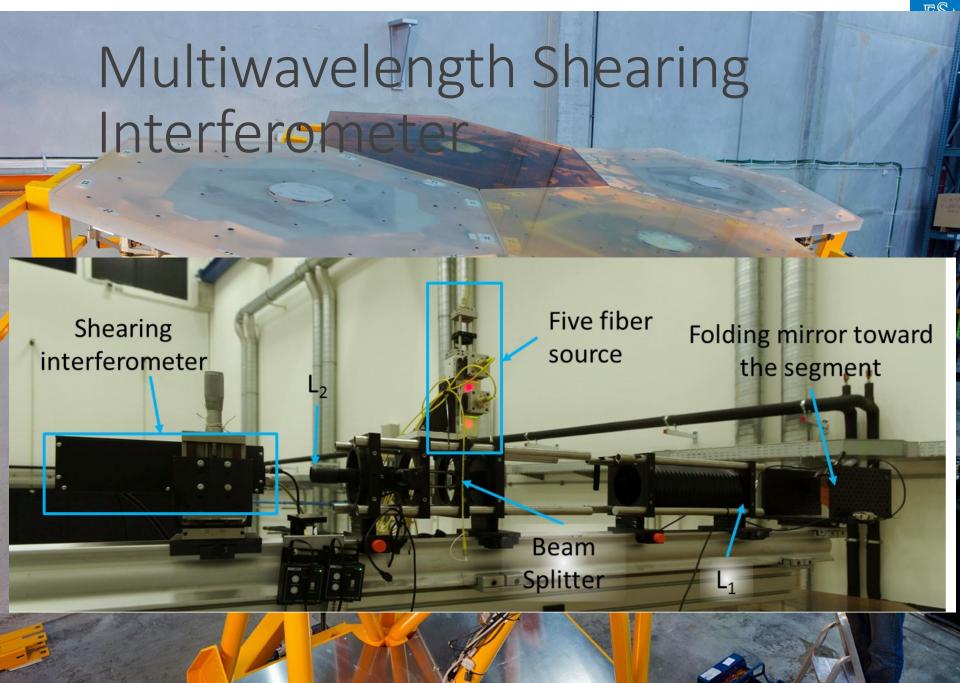
Five fiber

source ----

Folding

mirror_

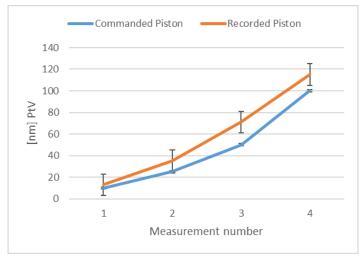




30/11/2017







To be done:

- \rightarrow Repeatability
- → Average of N measurements (dispersion)



Conclusion

On going & future work:

- PEACE refurbishment
 - AO cross performance
 - Zeus capture range increase -> wavelength scar
- Phasing gun
 - Miniaturisation
 - Dispersion characterisation

